

# Specification and Analysis of Requirements (SpeAR) Tool

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## What is SpeAR?

SpeAR is a functional requirements development framework with the following features:

- Formalisms to help users express requirements unambiguously.
- Domain-specific language to capture the contextual information.
- Constraint based analysis of formalized requirements against a set of validating properties.

## What isn't SpeAR?

- A detailed design tool.

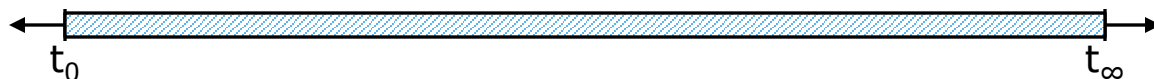
## Formalizing Requirements in SpeAR

SpeAR formalizes requirements using the specification patterns developed at Kansas State University.

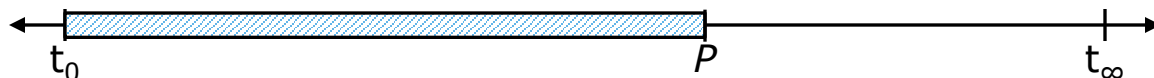
<http://patterns.projects.cis.ksu.edu/>

### Scopes

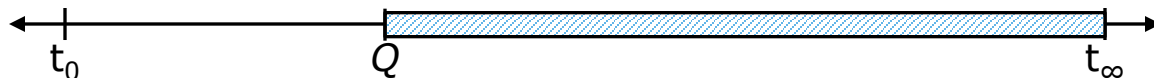
global



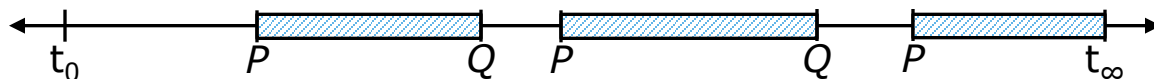
before  $P$



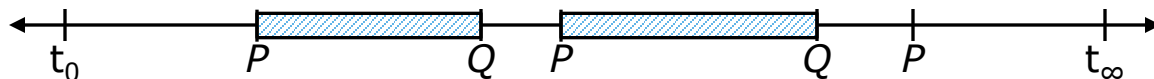
after  $Q$



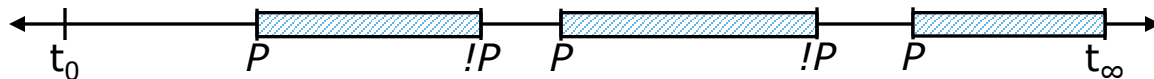
after  $P$  until  $Q$



between  $P$  and  $Q$

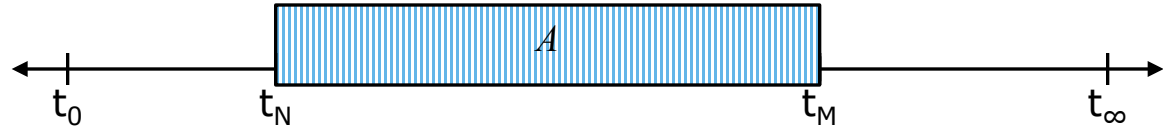


while  $P$



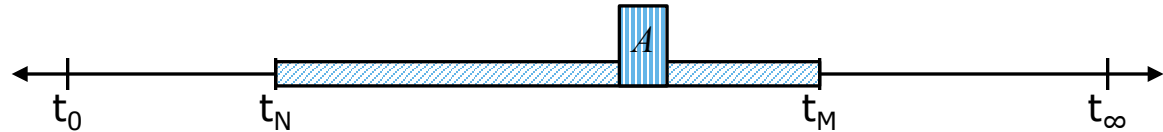
# Predicates

always A



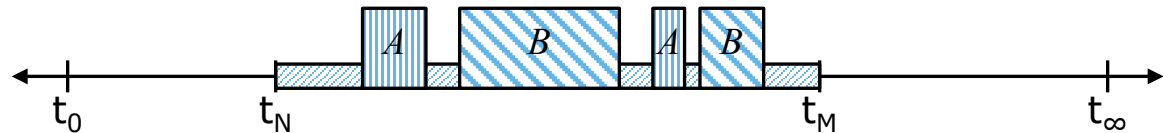
On the scope starting at  $[t_N, t_M)$  A must always hold.

exists A



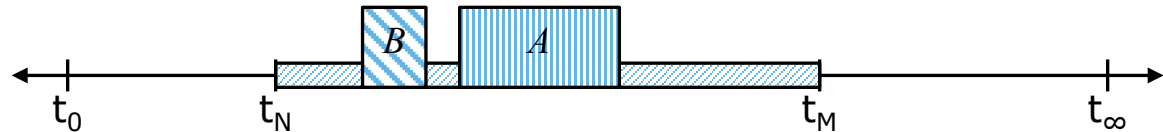
On the scope  $[t_N, t_M)$  A must hold at least once.

A precedes B



On the scope  $[t_N, t_M)$  every occurrence of B must be preceded by an occurrence of A.

A reponds B



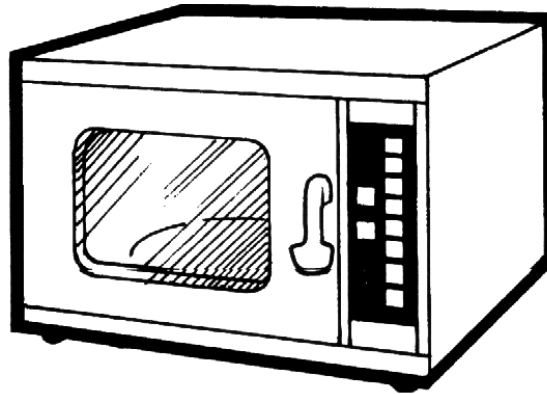
On the scope  $[t_N, t_M)$  every occurrence of B must be followed by an occurrence of A.

## Microwave Example

To illustrate the use of these patterns consider the example of a microwave oven. Describing the requirements of a microwave oven can be done in SpeAR.

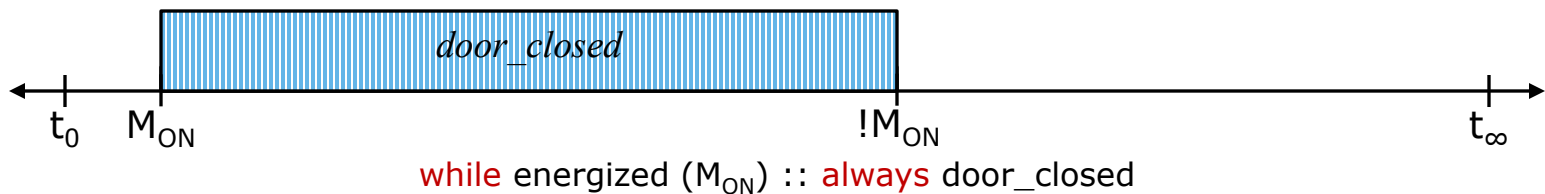
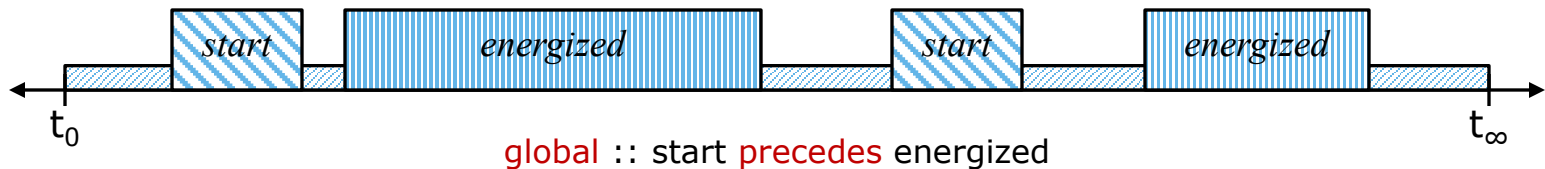
### Inputs

start  
clear  
door closed



### Outputs

energized  
time\_remaining



# Domain Specific Language

SpeAR specifications are captured in a domain specific language that requires explicit interface, assumptions and requirements definitions.

```

mode_logic.spear equals.spear
package microwave.mode_logic;

procedure mode_logic(clear,start,door_closed,seconds_to_cook) returns (output);

import microwave.definitions.*;
import microwave.definitions.mode_type;
import microwave.definitions.mode_type.*;
import microwave.definitions.modelogic_output_type;

Units:
  seconds;

State:
  clear : bool;
  start : bool;
  door_closed : bool;
  seconds_to_cook : int seconds;

  seconds_remaining : int;
  mode : mode_type;

  output : modelogic_output_type;

Requirements:
  a0 = global :: always (second_to_cook >= 0 seconds);

  r0 = initial :: (mode == SETUP) and (seconds_remaining == 0 seconds);

  r1 = after (pre mode == SETUP) :: (mode == SETUP) responds (not start or clear or seconds_to_cook <= 0 seconds);
  r2 = after (pre mode == SETUP) ::
    ((mode == COOKING) and (seconds_remaining == seconds_to_cook)) responds ( start and not clear and door_closed and seconds_to_cook > 0 seconds);
  r3 = after (pre mode == SETUP) ::
    ((mode == SUSPENDED) and (seconds_remaining == seconds_to_cook)) responds (start and not clear and not door_closed and seconds_to_cook > 0 seconds);

  r4 = after (pre mode == COOKING) :: ((mode == COOKING) and seconds_remaining == pre seconds_remaining - 1 seconds) responds
    ((pre mode == COOKING) and (door_closed and not clear and seconds_remaining > 0 seconds));
  r5 = after (pre mode == COOKING) :: (mode == SUSPENDED) responds (not door_closed or clear and (seconds_remaining > 0 seconds));
  r6 = after (pre mode == COOKING) :: (mode == SETUP) responds (seconds_remaining <= 0 seconds);

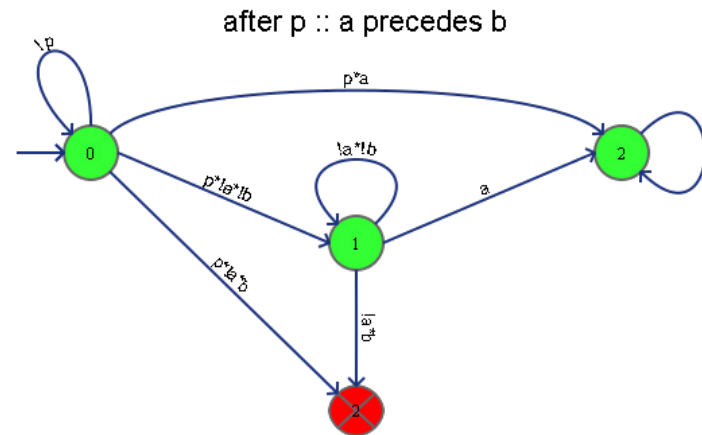
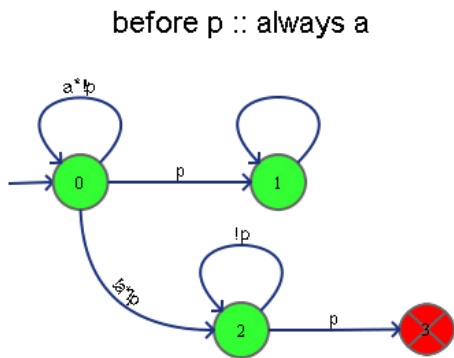
  r7 = after (pre mode == SUSPENDED) :: (( mode == SUSPENDED ) and (pre seconds_remaining == seconds_remaining)) responds
    (not start or not door_closed and not clear);
  r8 = after (pre mode == SUSPENDED) :: (mode == COOKING) responds (start and door_closed and not clear);
  r9 = after (pre mode == SUSPENDED) :: (mode == SETUP) responds clear;

  r10 = global :: always (output == modelogic_output_type {mode = mode, seconds_remaining = seconds_remaining});

Properties:
  p1 = while (mode == COOKING) :: always door_closed;
  p2 = before start :: always (mode == SETUP);
  p3 = while ((mode == COOKING) or (mode == SUSPENDED)) :: always (seconds_remaining <= pre seconds_remaining);
  p4 = global :: always (mode <> COOKING);
  
```

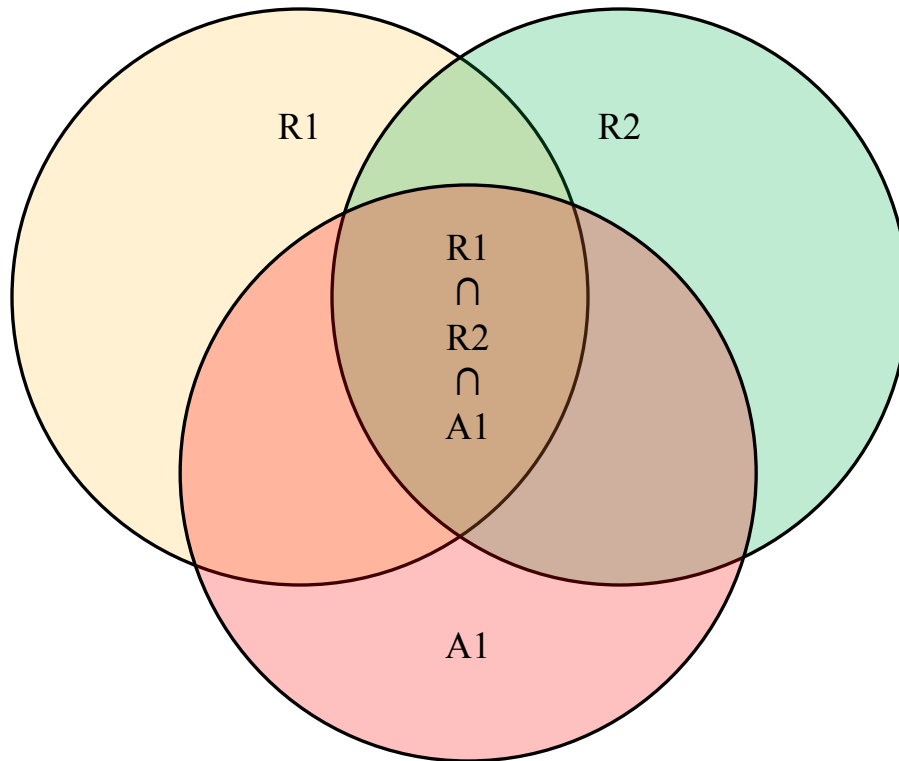
## Representing the Patterns in Lustre for Analysis

Each property is translated into a finite state machine. The green states denote accepting states, the red states failed states, and the grey states are non-accepting.



## Analysis in SpeAR

The intersection of the set of traces that our requirements accept defines the set of traces our system accepts. If a property P also accepts that set of traces, the system satisfies the property.



If a property P also accepts that set of traces our system satisfies that property.



# Counterexamples

Analysis results are provided to the user in a graphical interface. If a property is violated by the requirements a trace is provided to the user for debugging.

Analysis Results

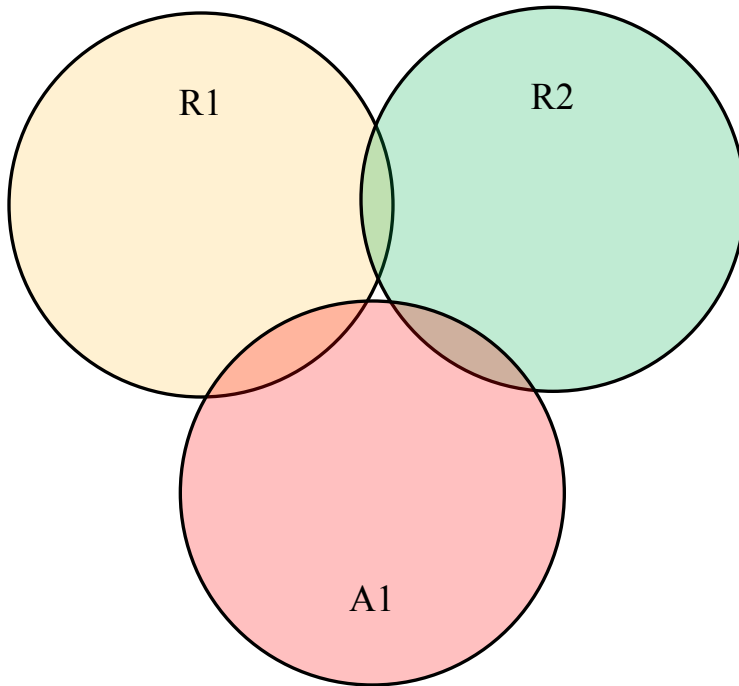
Property	Result
<span style="color: red;">❌</span> p3	Invalid (0s)
<span style="color: green;">✅</span> p1	Valid (0s)
<span style="color: green;">✅</span> p2	Valid (0s)

Step	A	B	C	D
1	Step		0	1
2				
3	<b>Signals</b>			
4	Assumptions and requirements.	TRUE	TRUE	
5	Enforces that assumptions and requirements are always true.	TRUE	TRUE	
65	clear	FALSE	FALSE	
66	door_closed	FALSE	TRUE	
73	mode		0	1
74	output_mode		0	1
75	output.seconds_remaining		0	1
76	p3	TRUE	FALSE	
77	r0	TRUE	TRUE	
78	r1	TRUE	TRUE	
79	r10	TRUE	TRUE	
80	r2	TRUE	TRUE	
81	r3	TRUE	TRUE	
82	r4	TRUE	TRUE	
83	r5	TRUE	TRUE	
84	r6	TRUE	TRUE	
85	r7	TRUE	TRUE	
86	r8	TRUE	TRUE	
87	r9	TRUE	TRUE	
88	seconds_remaining		0	1
89	seconds_to_cook		1	1
90	start	FALSE	TRUE	

## Realizability

If there is no set of traces that satisfy the intersection of the requirements set, the set is not realizable. SpeAR (in-progress) will be able to identify unrealizable specifications.



If there is no set of traces that all the requirements and assumptions accept, the system is not realizable.

## Download Spear, it's open source!

<http://www.github.com/afifarek/spear>

Check out the releases tab, or build from source using Eclipse.

## Questions?

